

# Iterative Methods for Elliptic Equations with Varying Coefficients

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# Overview

- elliptic equation with variable coefficient  $\alpha \succ 0$

$$\nabla \cdot (\alpha \nabla u) = f$$

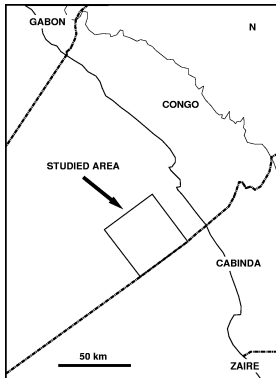
- highly varying  $\alpha$
- motivation : flow in porous media
- finite element discretisation
- large system of equations

$$\mathbf{A}u = \mathbf{f}$$

- multilevel iterative methods

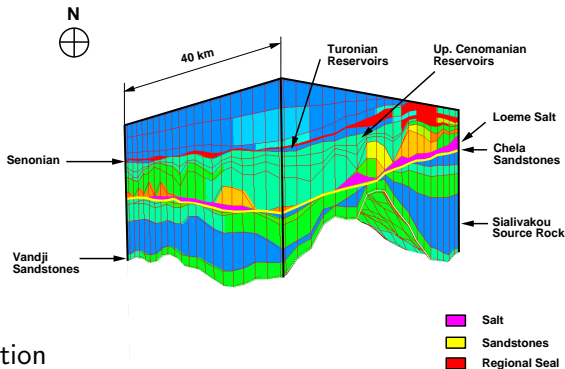
# Motivation: Sedimentary Basin Simulation

F. Schneider et al., *Oil & Gas Science and Technology* 55(1), 2000



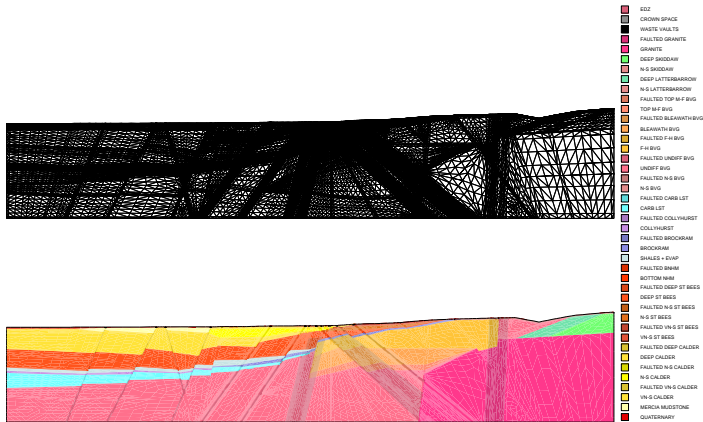
Position

of the studied area in  
the Congo offshore



of the studied 3D-block

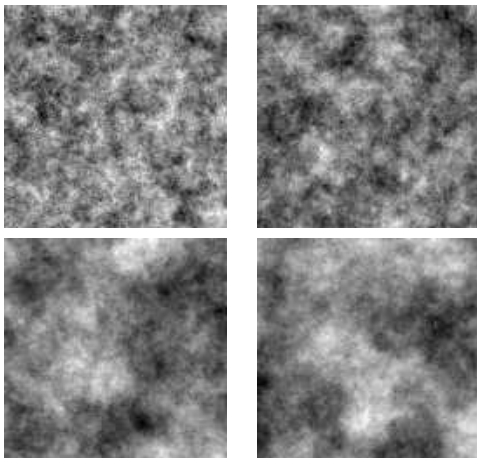
# Motivation: Groundwater Flow (Sellafield)



# Motivation: Stochastic Model

Cliffe, Graham, Scheichl, Stals, 2000

- lognormal Gaussian random field
- variance  $\sigma^2$  : *contrast*
- length scale  $\lambda = 5, 10, 20, 50$  : *roughness*



# Solving the System of Equations

- system of equations

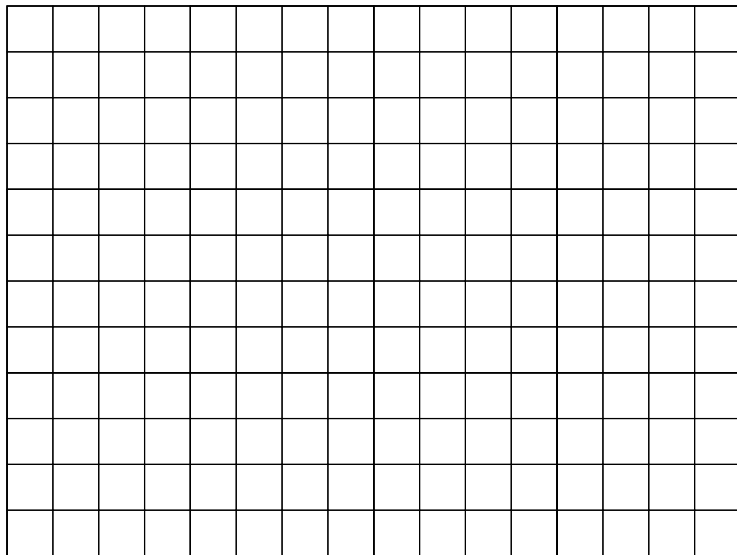
$$Au = f$$

- $A$  is symmetric positive definite
- $A$  is large, but sparse and structured
- 1D, linear elements: tridiagonal
- 2D, regular grid, linear elements:  
block tridiagonal with tridiagonal blocks
- direct solvers for 1D, maybe 2D, not 3D
- constant coefficients: (block-)Toeplitz, FFT
- unstructured grids, varying coefficients:  
multilevel iterative methods

# Domain Decomposition Methods

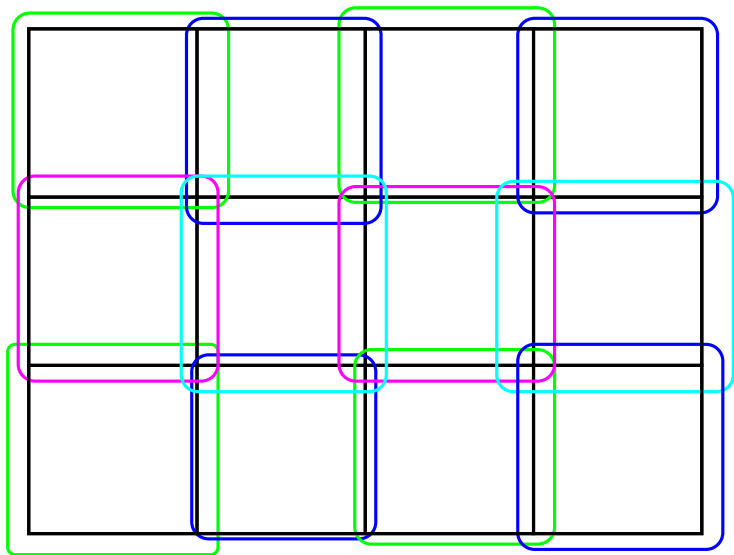
- whole system too much for direct solver (or 1 computer)
- decompose the problem into smaller subproblems
- subproblems are coupled: iteration
- divide domain into smaller subdomains
- many different types
- here overlapping additive Schwarz method
  
- aim: scalable and robust methods  
number of iterations and cost per iteration well behaved w.r.t.
  - ▶ problem size
  - ▶ number of subdomains
  - ▶ coefficients!
  
- ideally for  $N$  unknowns:  
 $O(1)$  iterations,  $O(N)$  operations per iteration

# Grid

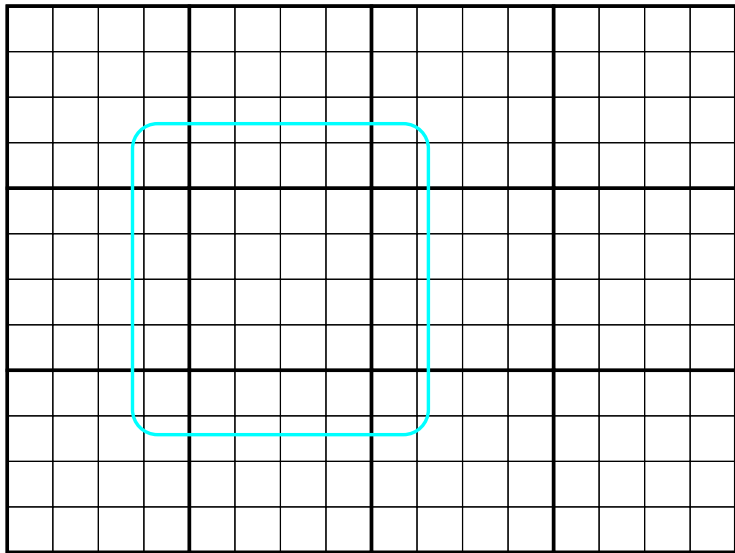




# Overlapping Subdomains

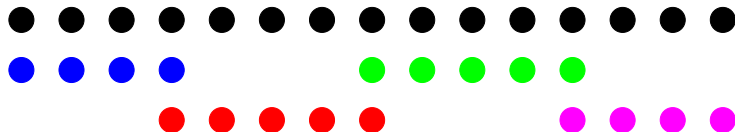


# Subdomain



# Formulation of the One-Level Method

- CG for  $A$  with preconditioner  $B$
- only matrix-vector products for  $A$  and  $B$
- number of iterations  $\sim \kappa(BA)$
- overlapping subdomains

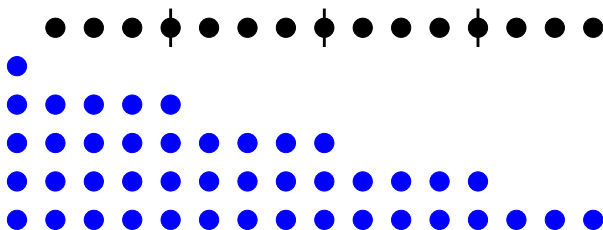


- overlapping additive Schwarz method

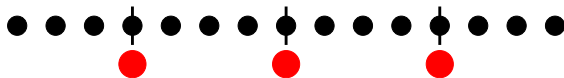
$$\begin{aligned}y &= Bx \\ &= \sum_i R_i^T A_i^{-1} R_i x\end{aligned}$$

# Convergence of the One-Level Method

- not scalable
- illustrate with 1D problem
- rhs  $f = 0$ , BC  $u(0) = 1$ ,  $u(1) = 0$ , start with  $u^0 = 0$
- information moves at rate of 1 subdomain per iteration



- number of iterations depends on number of subdomains
- remedy: in addition to local solves, do global solve



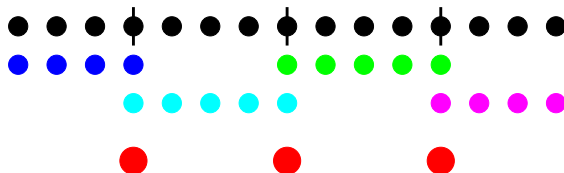
# Formulation of the Two-Level Method

- fine level: subproblems that together cover the whole problem

$$B = \sum_i R_i^T A_i^{-1} R_i$$

- coarse level: one smaller problem for the whole domain

$$\hat{B} = R_0^T A_0^{-1} R_0$$



- two-level preconditioner

$$\tilde{B} = \hat{B} + B$$

# Choice of Coarse Space

- choice of  $R_0$  is very important for good convergence
- incorporate coefficients
- from theory we know that
  - ▶ energy of basis functions must be low
  - ▶ basis functions must preserve constants
- set up constrained minimisation problem
- columns of  $R_0^T$

$$R_i^T A_i^{-1} R_i g$$

- where

$$Bg = \mathbf{1}$$

- how to solve this system?

# One-Level Preconditioner for the One-Level Preconditioner

- $B$  has special structure, “local” operator
- no global solve needed
- construct one-level preconditioner for  $B$
  
- matrix  $A$
- one-level preconditioner  $B = \sum_i R_i^T A_i^{-1} R_i$
- local problems for  $A_i = R_i A R_i^T$
- one-level preconditioner  $C = \sum_j R_j^T B_j^{-1} R_j$
- local problems  $B_j = R_j B R_j^T$

# Efficiency and Robustness

- $A_i$  sparse  $\rightarrow Bx$  efficient
- $B_i$  dense
- $B \sim A^{-1}$  and  $C \sim B^{-1}$  so somehow  $C \sim A$
- $Cx$  can be implemented efficiently
- number of iterations  $\sim \kappa(CB)$
- constructing  $R_0$  is scalable and robust



# Summary

- considered elliptic equations with varying coefficients
- very large systems of equations
- two-level preconditioner
- construction is not cheap, but algebraic, scalable and robust
- main ideas
  - ▶ one-level preconditioner for one-level preconditioner
  - ▶ efficient implementation
- topics for further research
  - ▶ for overall scalability and robustness, it is important to choose the subdomains well
  - ▶ non-symmetric systems